IN THE SPECIFICATION

Please amend the paragraph beginning at page 1, line 27, as follows:

In an image data input apparatus utilizing the solid state image forming device 101, the positional accuracy of line of pixels becomes very important because there is an importance that a line image from an image focusing lens 104 is focused on the pixels of the solid state image forming device 101 while the predetermined accuracy in the optical characteristics are fulfilled in order to realize better image input performance. To attain this, the position of the solid state image forming device 101 with regard to the image focusing lens 104 must be adjusted with a slight movement in five axes of x, y, z, [[B]] $\beta$ and [[$_Y$]] $\gamma$ respectively as shown in Fig. 9. Generally, it is requested that the positional accuracy of the solid state image forming device 101 of this kind is highly accurate in the five axes.

Please amend the paragraph beginning at page 17, line 2, as follows:

Herein, directions are defined as z axis is a direction which is parallel to the optical axis 9 of the image focusing lens 2, x axis is a direction which is a first scanning direction of the image data input apparatus, in other words, the line of pixel extending direction, and y axis is a direction which is a second scanning direction, in other words, the direction perpendicular to the x-z plane. Also, a rotational direction around the y axis is defined as [[B]] $\beta$ direction and a rotational direction around the z axis is defined as [[$_Y$]] $\gamma$ direction.

Please amend two paragraphs beginning at page 18, line 14, as follows:

This caulking adhering method is made after a positional adjustment between the image focusing lens holding member 3 and the solid state image forming device 1 in the five axes of x, y, z, [[B]] $\beta$ and [[$_Y$]] $\gamma$, and hereinafter the process of it will be described.

Firstly, the solid state image forming device 1 and the image focusing lens holding member 3 are respectively fixed with a predetermined and adjusted positional relation on stages on which a fine positional adjustment in three dimension can be achieved. (Hereinafter, this stage is referred to as "fine adjustment stage".) On the fine adjustment stage onto which the solid state image forming device 1 is fixed, the fine adjustment in x, z and [[B]] $\beta$ as shown in Fig. 1 can be achieved, and on the fine adjustment stage onto which the image focusing lens holding member 3 is fixed, the fine adjustment in x, y and [[$\gamma$]] $\gamma$ as shown in Fig. 1 can be achieved.

Please amend the paragraph beginning at page 20, line 9, as follows:

In this state, the adhering surface between the solid state image forming device 1 and the intermediate holding member 6 is substantially parallel to the x-z plane, and the solid state image forming device 1 is restricted by the second adhering surface 6b of intermediate holding member 6 which is substantially parallel to x-z plane for moving in any direction other than x, z and [[B]] $\beta$, and in these directions the fine positional adjustment can be achieved. Herein, the adhering surface between the image focusing lens 3 and the first adhering surface 6a of intermediate holding member 6 is substantially parallel to the x-y plane, and the image forming lens holding member 3 is restricted by the first adhering surface 6a of intermediate holding member 6 which is substantially parallel to x-y plane, for moving in any direction other than x, y and [[$\gamma$]] $\gamma$, and in these directions the fine positional adjustment can be achieved. In these consequence, the relative positional relation between the solid state image forming device 1 and the image focusing lens 3 can be easily and precisely adjusted through the intermediate holding member in the five direction of x, y, z,

[[B]] $\beta$ and [[$_Y$]] $\gamma$.

Please amend the paragraph beginning at page 25, line 4, as follows:

In this variation 4 of example because the adhering surface 5 between the image focusing lens holding member 3 and the intermediate holding member 6 is parallel to x-z plane, and the adhering surface between the intermediate holding member 6 and the solid state image forming device 1 is parallel to x-y plane, because the image focusing lens holding member 3 and the solid state image forming device 1 can have the positional adjustment in direction of the five axes of x, y, z, [[B]] $\beta$ and [[$_Y$]] $\gamma$, the accurate positional distribution can be attained as the above described examples of the present invention.